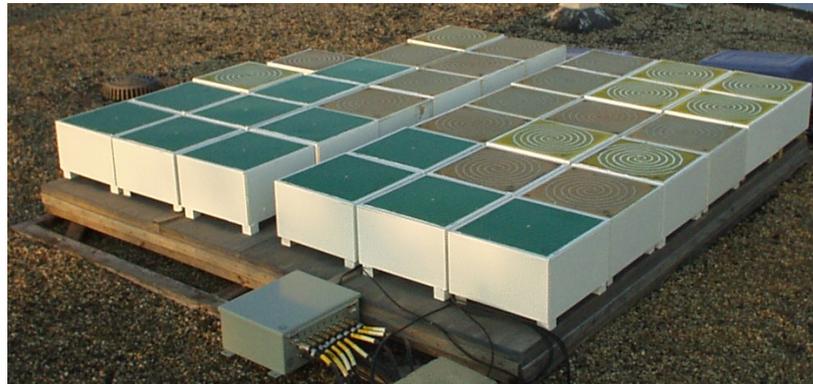


Detection & Localization of L-Band Satellites using an Antenna Array



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June 2004



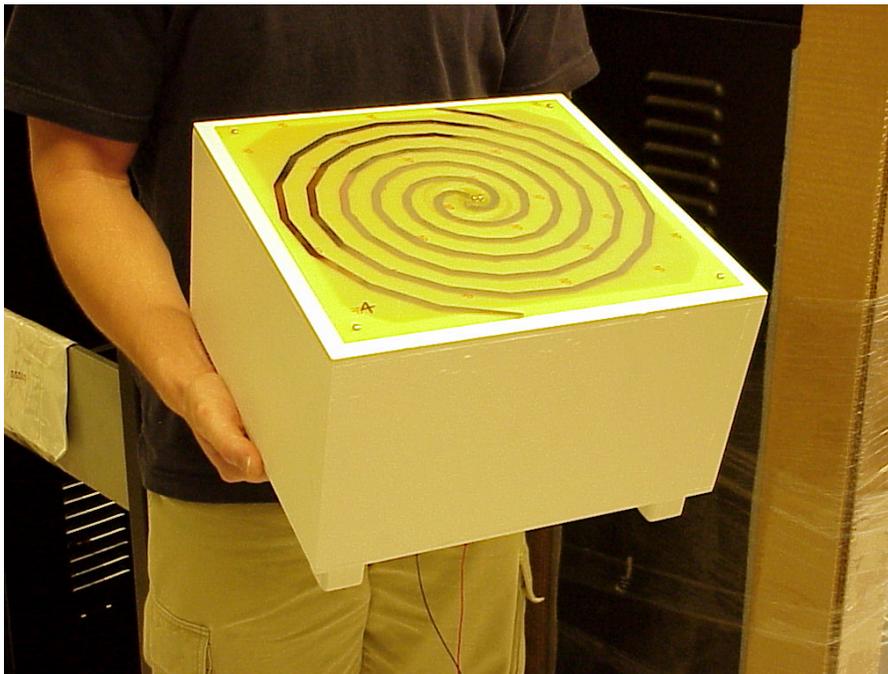
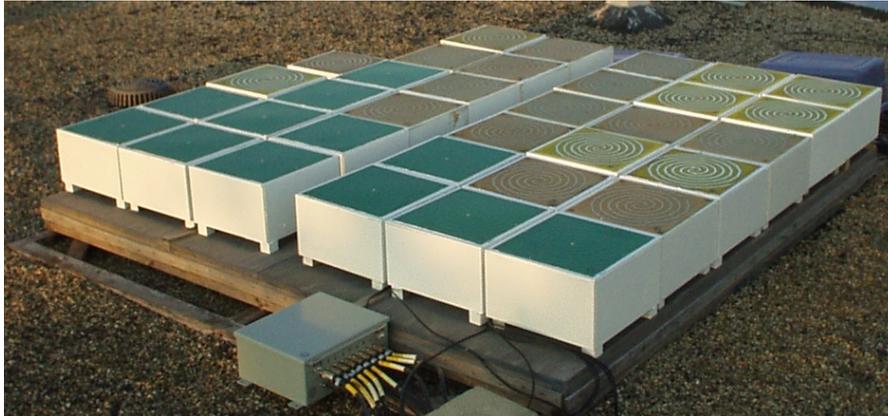
<http://www.ece.vt.edu/~swe/argus>

Introduction

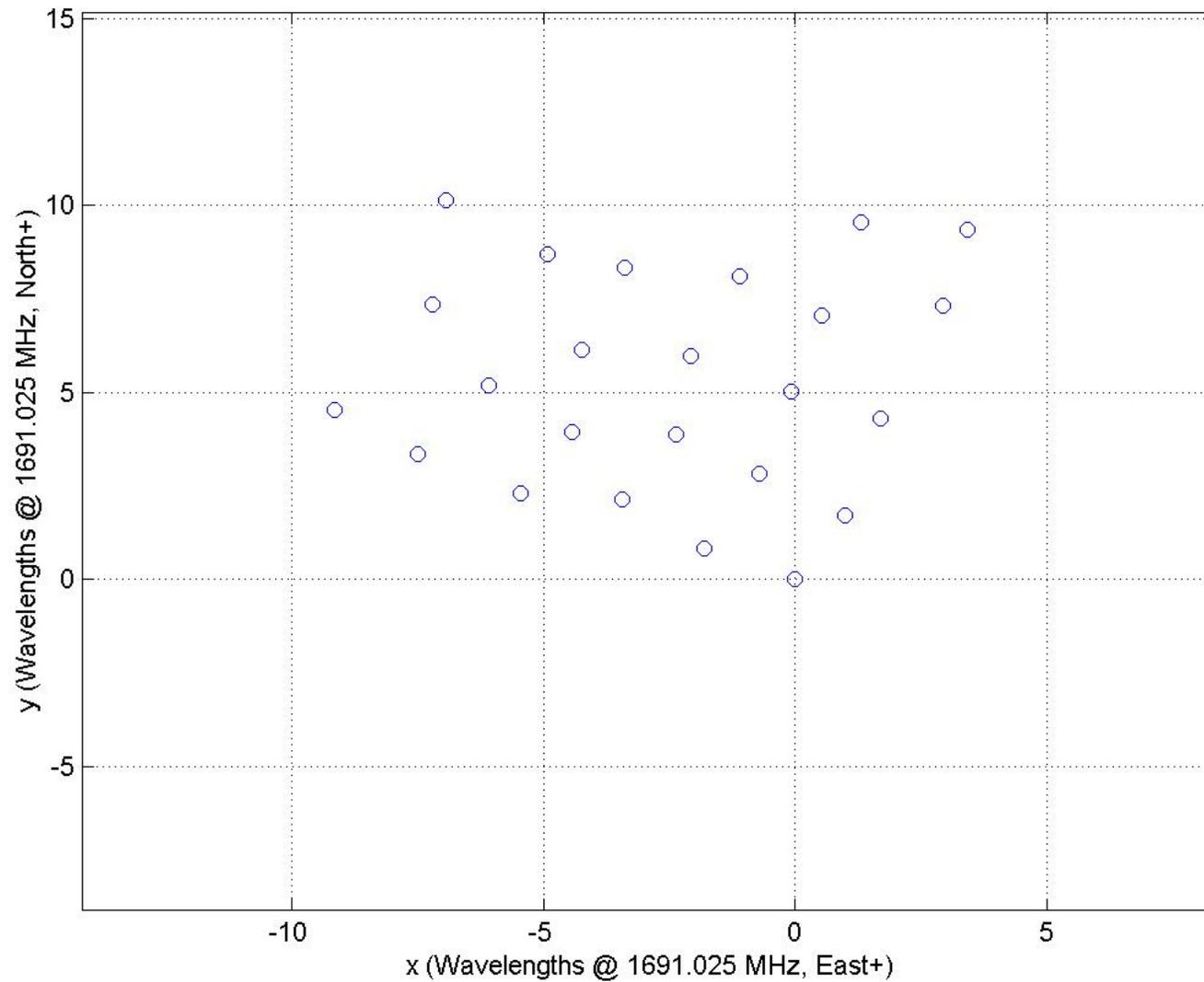


- **Traditional radio astronomy uses large, filled-aperture antennas to achieve high sensitivity and spatial resolution.**
- **The resulting field of view (FOV) is extremely narrow, which limits sensitivity to undiscovered transient astronomical sources.**
- **An alternative approach is to use instead large numbers of low gain (broadbeam) elements to achieve sensitivity over the entire sky.**
- **Our system “Argus” is a first step in that direction. The system has been continuously operational since Spring 2003.**
- **Here, we present some work in validating system performance using observations of earth-orbiting satellites.**

Antenna Array



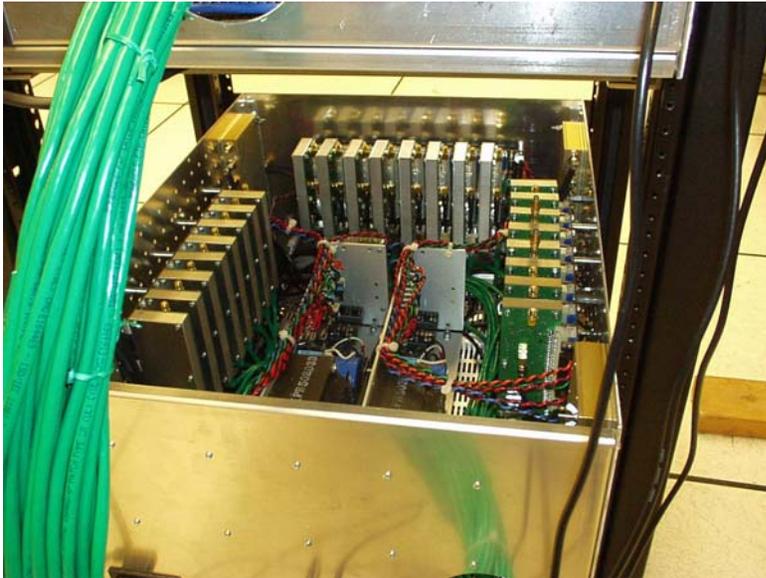
- 34 antenna units in array (currently in a pseudo-random configuration); 24 are operational
- Element is planar spiral on FR4 with tiered ground plane
- $A_e \sim 60 \text{ cm}^2$ per antenna @ 1420 MHz, zenith
- Integrated LNA powered through RF cable
- $T_{\text{sys}} \sim 215 \text{ K}$ per element
- Total useable range about 900-1700 MHz



Array geometry.

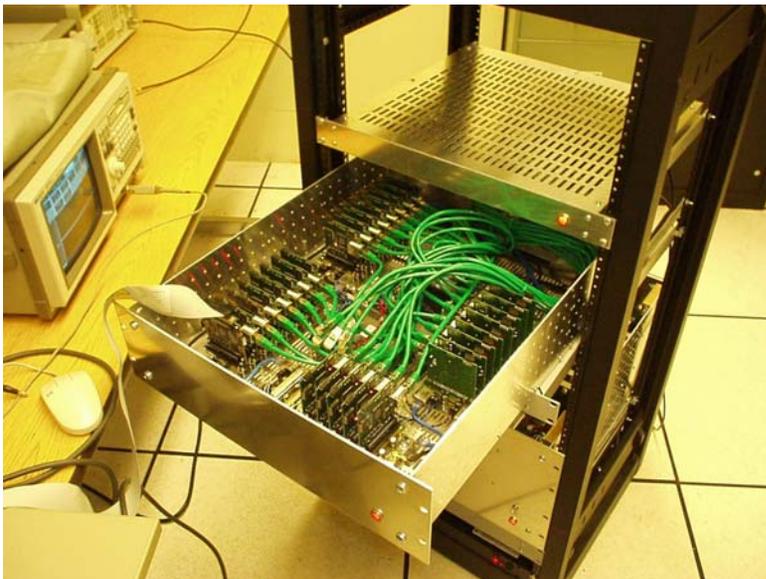
Approximately random so as to mitigate aliasing as much as possible.
Dots represent phase centers of elements employed in this experiment.

Receivers / Data Aggregation



Direct Conversion Receivers (DCRs)

- Moves 14 MHz spectrum from L-band to baseband (I/Q)
- Digitizes 20 MSPS, 8-bit “I” + 8b “Q”
- Output at 320 Mb/s using serial LVDS



Argus Narrowband Processor (ANP)

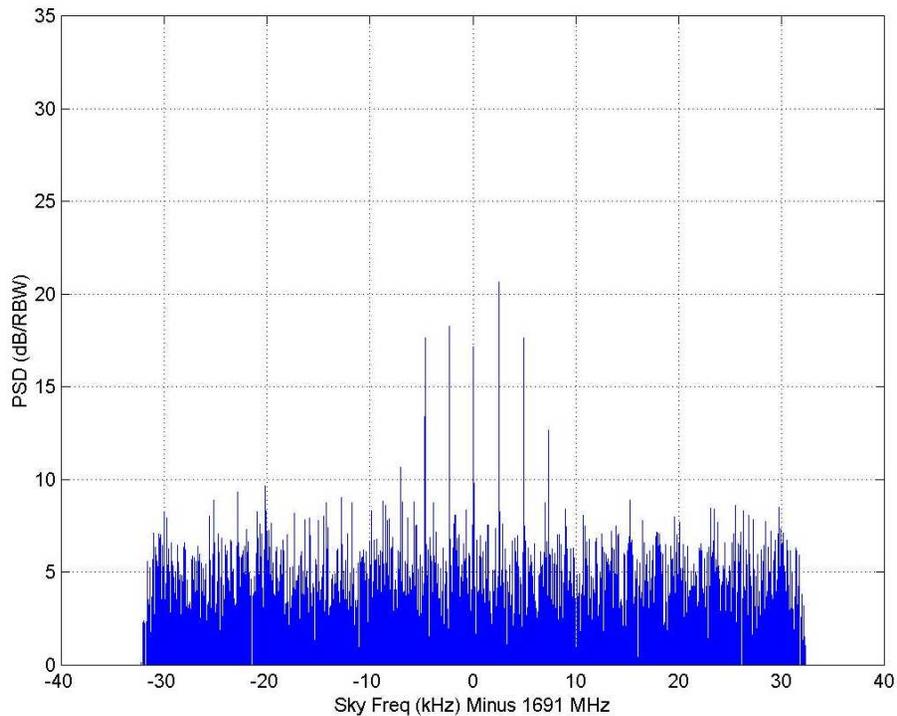
- Corrects (small) I/Q imbalance from DCRs
- “Tune and Zoom” within 14 MHz digital passband: 60 kHz BW @ 78.125 kSPS
- Continuously aggregates 32 elements in a single data stream; further processing by a PC cluster

<http://www.ece.vt.edu/~swe/argus>

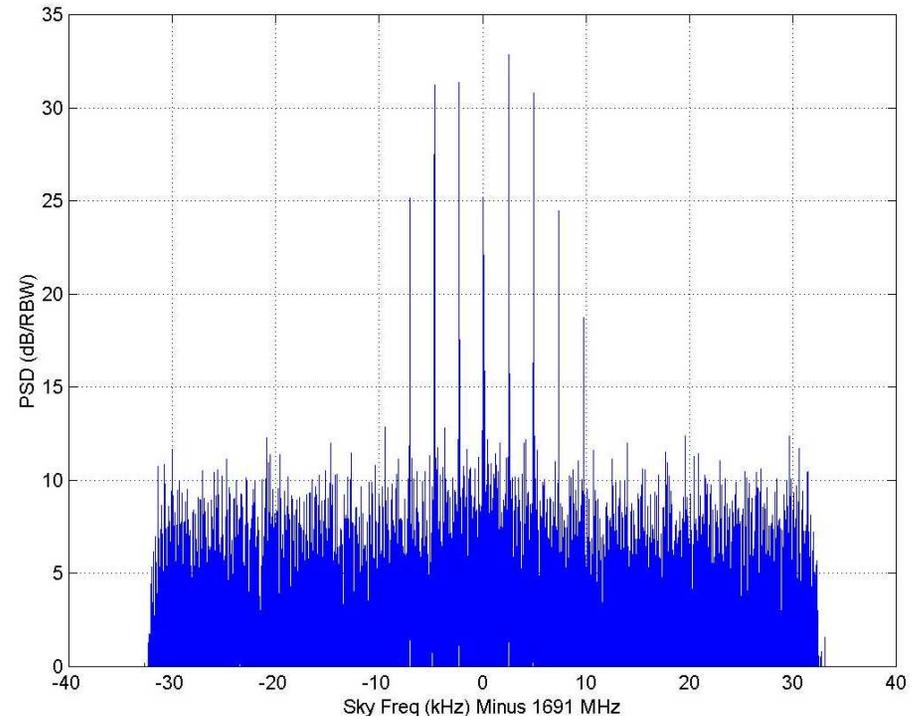
Adaptive Beamforming Example



- 1691 MHz (WEFAX) emission from geostationary satellite GOES-EAST
- Relatively weak signal (normally requires 1-m dish and good LNA)

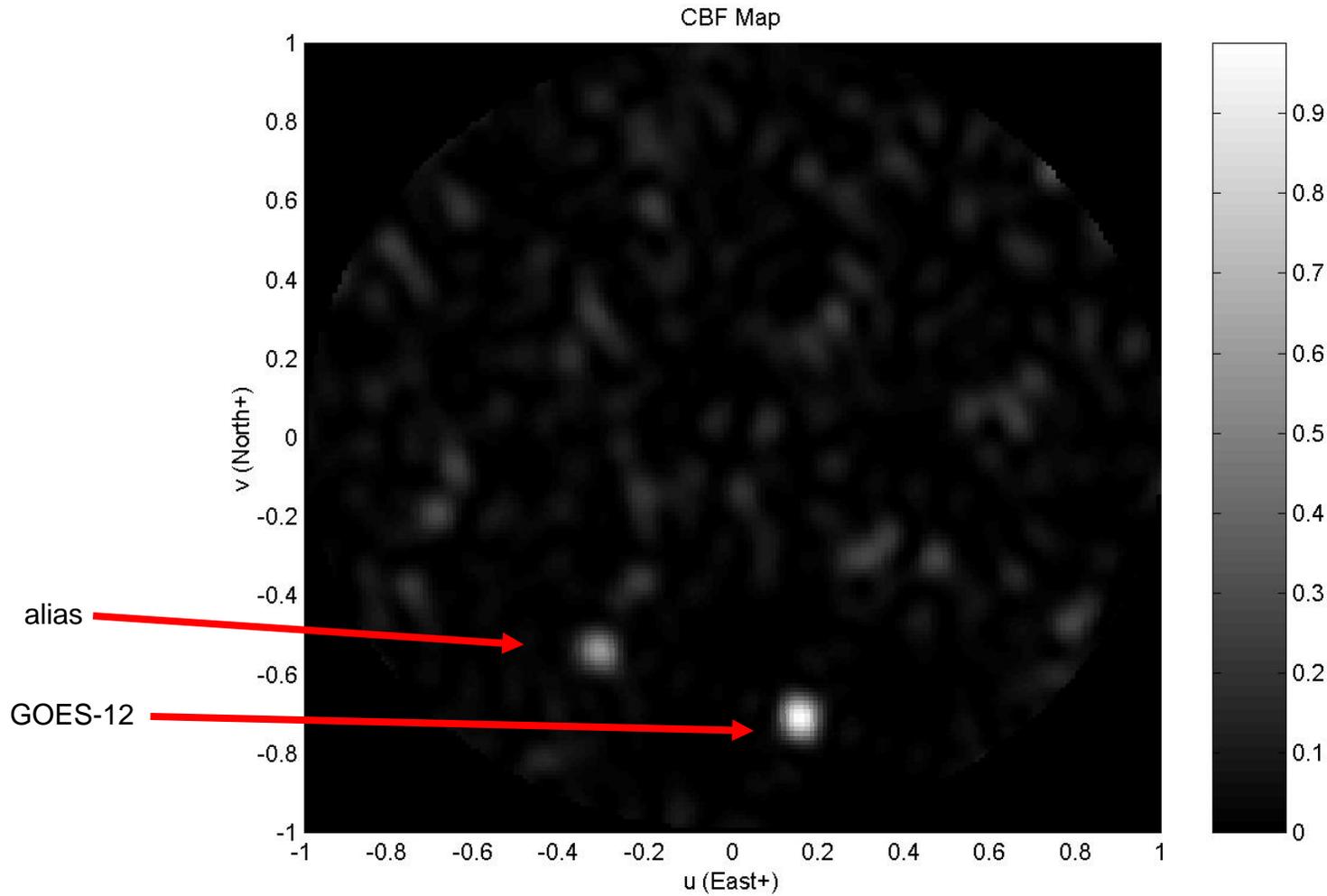


Signal from single element



Signal after beamforming with 24 elements, using adaptively estimated weights

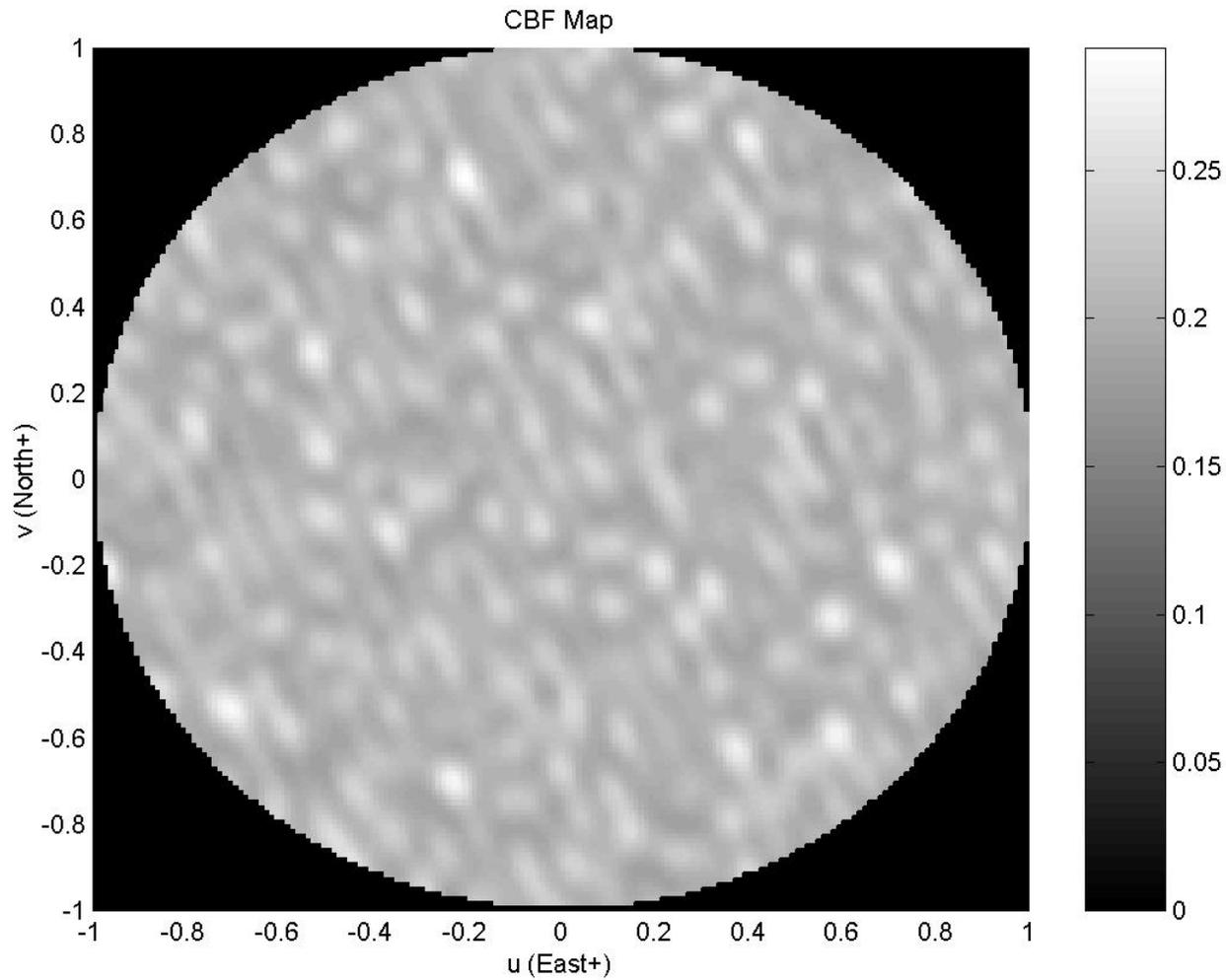
Imaging Example



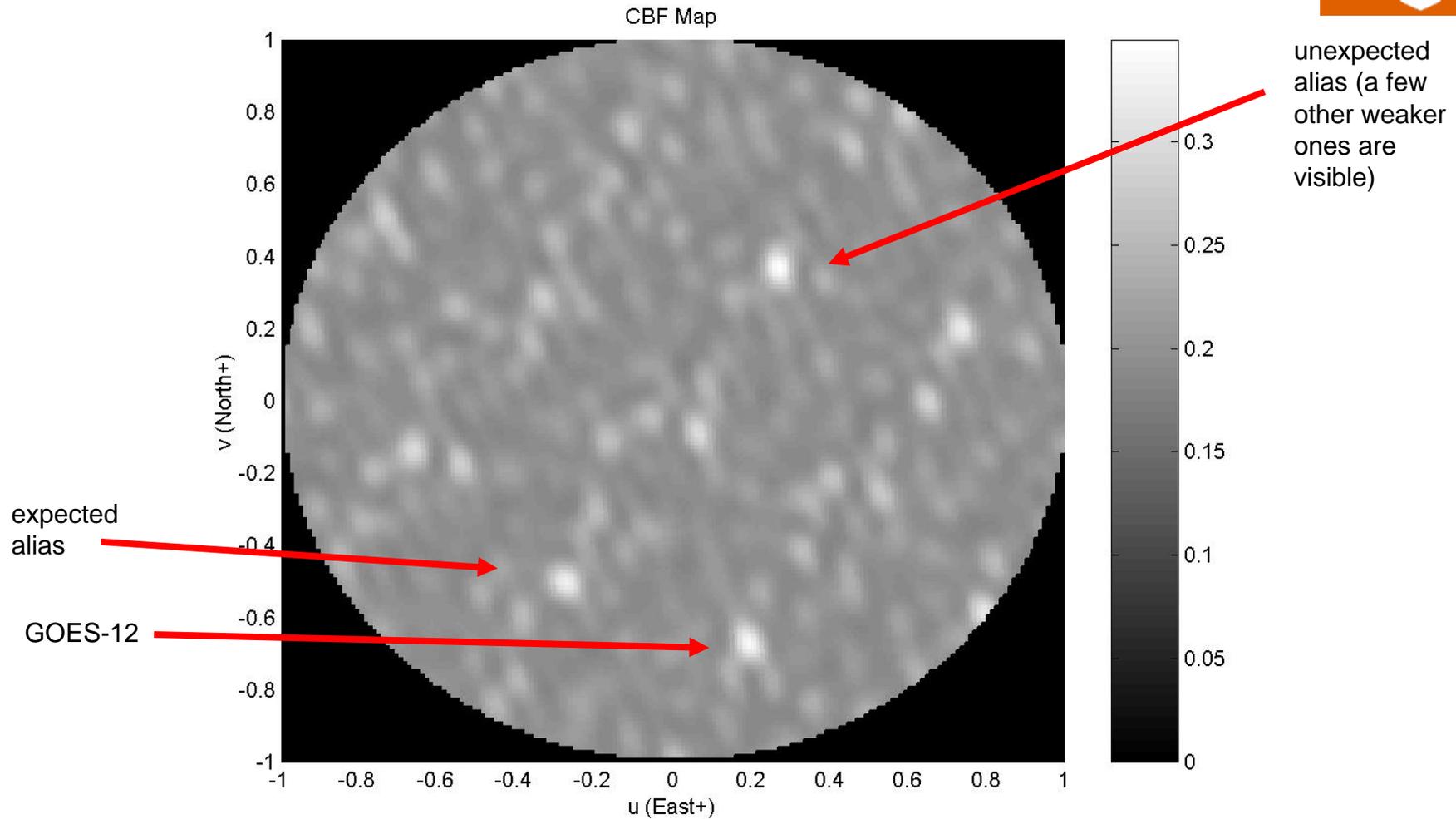
Predicted result for GOES-12 (1691.0 MHz), **obtained from simulation**.
Note strong alias plus complex sidelobe structure.

How to interpret image: u (horizontal axis) and v (vertical axis) are "direction cosines": $u=v=0$ is the zenith, and $u^2+v^2=1$ is the horizon.

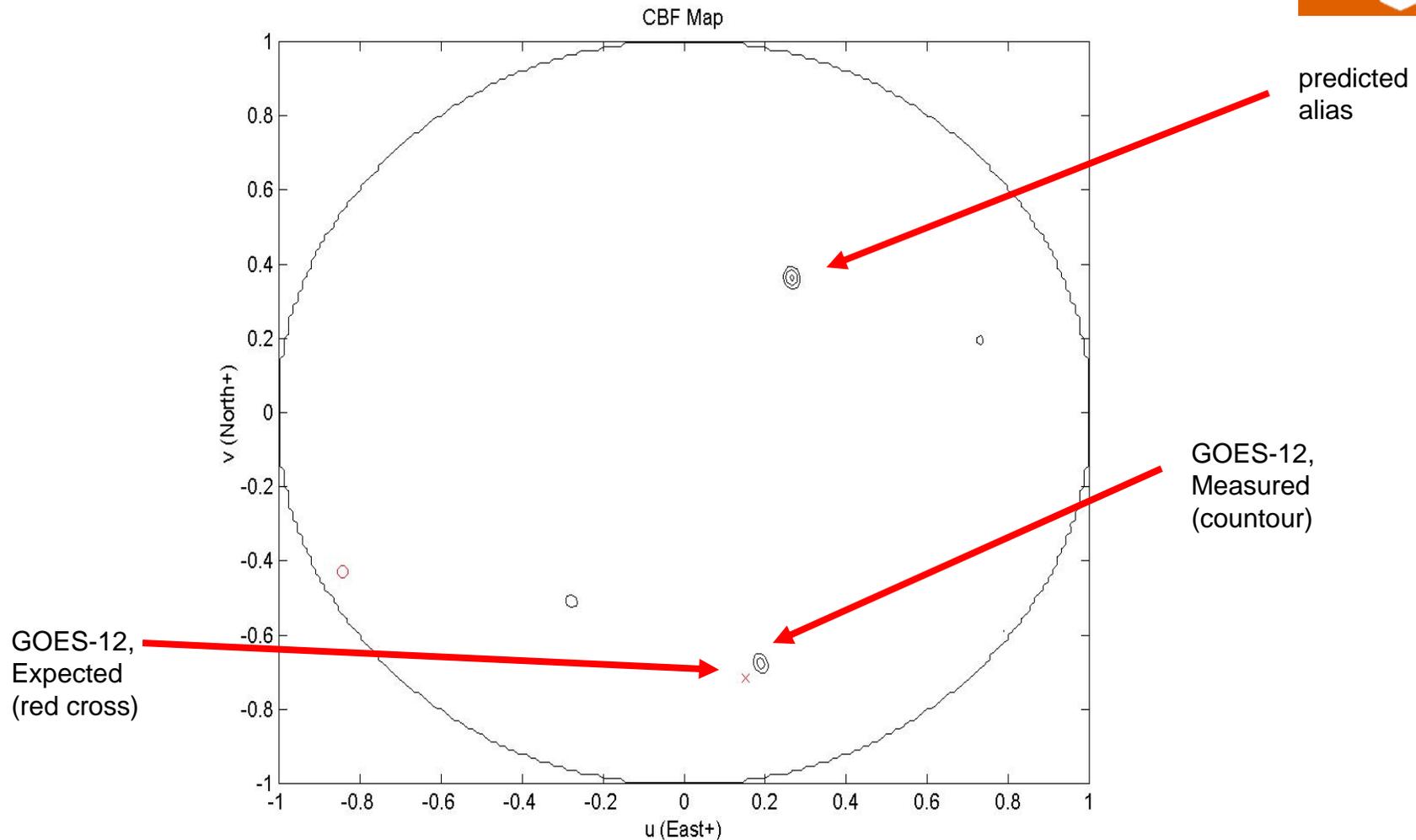
<http://www.ece.vt.edu/~swe/argus>



**Actual measured result at 1691.0 MHz, 30 kHz bandwidth,
before calibration.**



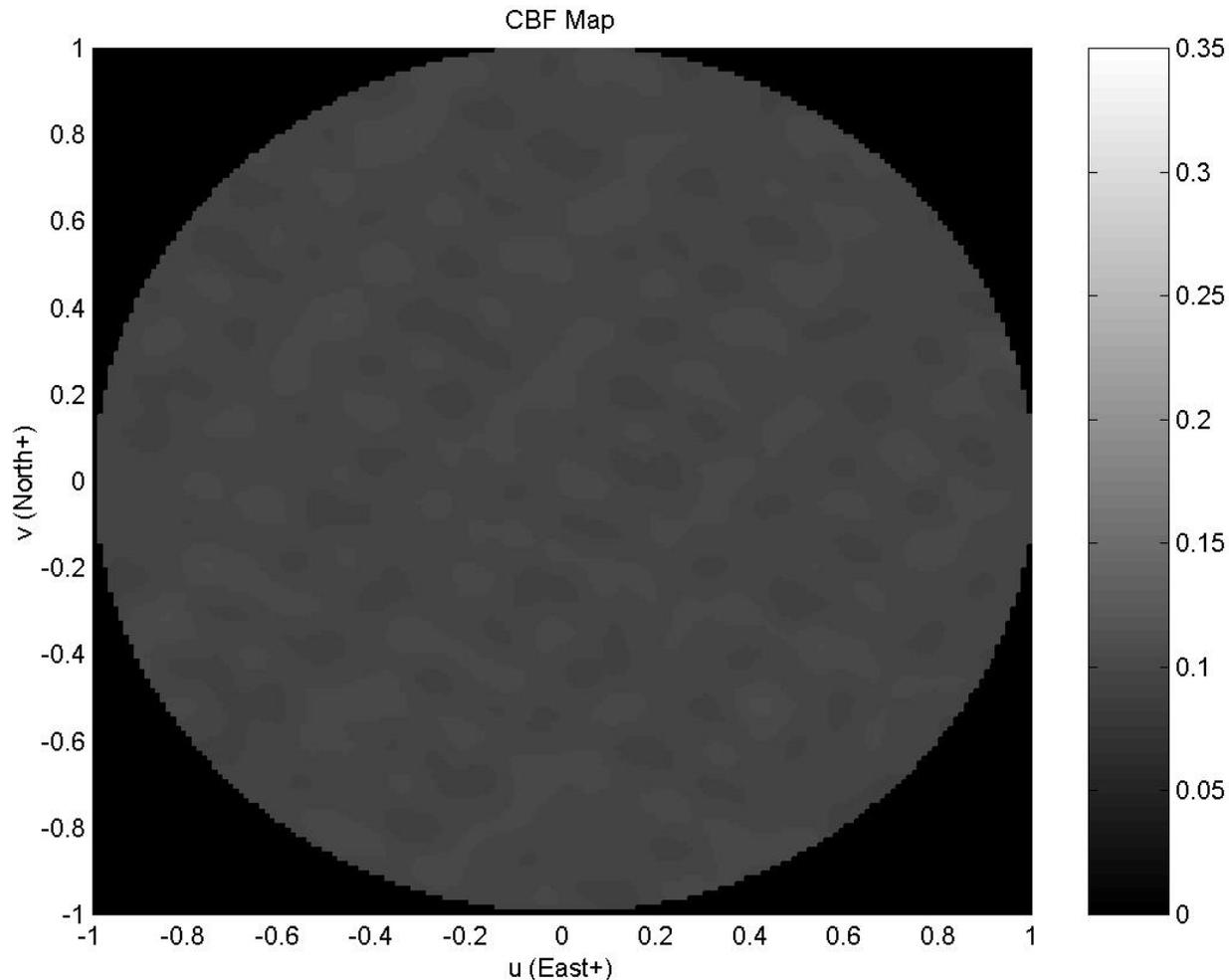
**Actual measured result at 1691.0 MHz, 30 kHz bandwidth,
calibrated using near-field noise source.**



Actual measured result at 1691.0 MHz, 30 kHz bandwidth, calibrated.

This is a contour plot derived from the GOES-12 measured image, with contours at 0.99, 0.95, 0.90, and 0.10 times the brightest pixel.

Small misalignment is probably due to error in measuring array geometry.



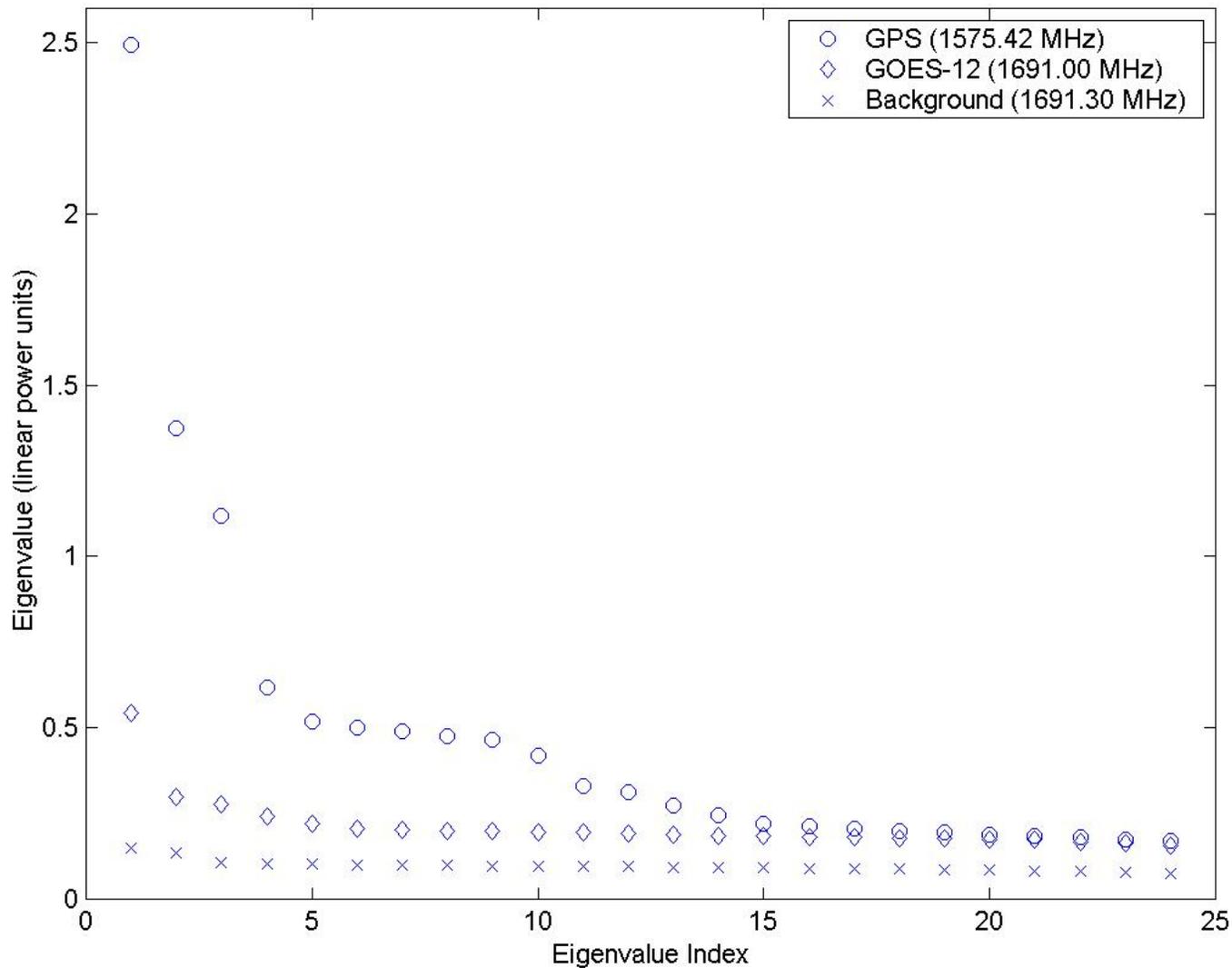
Actual measured result at 1691.3 MHz, 30 kHz bandwidth, calibrated.

By observing the adjacent 30 kHz channel, which is nominally signal-free, we confirm that the system is fairly well calibrated (indicated by the relatively flat image) and that all structure seen in the previous image is due to GOES-12.

Detection by Eigenanalysis



- A 24 x 24 “spatial covariance matrix” R , tabulating the cross-correlations between all possible pairs of elements, is formed from a single 209-ms data record.
- Assuming perfect calibration, the absence of a signal means all of the eigenvalues of R are equal.
- Thus, detection can be defined as a condition in which the inequality of eigenvalues exceeds some threshold.
- The number of eigenvalues exceeding this threshold indicates the number of uncorrelated far-field sources detected.
 - At 1691.00 MHz, we should detect 1 signal (GOES-12 WEFAX)
 - At 1691.30 MHz, we should detect 0 signals (Cold sky)
 - At 1575.42 MHz, we should detect ~9 signals (GPS constellation)



Observed eigenvalue spectra, 209 ms integration

Observed signal to noise ratios are consistent with anticipated 215 K / element system temp.

Concluding Remarks

- **Argus system functions and sensitivity have been validated using observations of earth-orbiting satellites**
 - Sensitivity $\sim (2.4 \times 10^{-22} \text{ W m}^{-2} \text{ Hz}^{-1})$ in 209 ms

- **Should be noted that same detection performance can be achieved without calibration! (Only the difference relative to a “noise-only” spatial covariance is important.)**

- **Work continues on implementing a campaign to detect & localize astronomical transients**
 - Present limitation is (ironically) interference from terrestrial- and space-based transmitters

- **Same technology has many other applications**
 - **Interference surveillance and characterization**
 - Radio astronomy
 - Spectrum management / regulatory activity
 - **Passive multistatic radar**
 - Military / National security
 - Civilian aviation